(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

Lesson Plan

Name of the Subject: Adaptive Signal Processing (14MT26101) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: Mr T.Ravisekhar

| S. | Торіс | No. of | Book(s) | Topics for self study |
|-----|---|-----------|-----------|---|
| No. | | periods | followed | |
| UN | T - I: INTRODUCTION TO ADAPTIVE SY | YSTEMS& [| DEVELOPMI | ENT OF ADAPTIVE |
| | FILTER T | HEORY | I | |
| 1. | Definitions, Characteristics, | 1 | T2 | Hermittan Matrix |
| | Applications, Example of an Adaptive | | | Properties |
| | System | | | |
| 2. | The Adaptive Linear Combiner | 1 | T2 | |
| 3. | Weight Vectors, Desired Response Performance function | 1 | T2 | |
| 4. | Gradient & Mean Square Error | 1 | T2 | |
| 5. | Introduction to Filtering, Smoothing and Prediction, Problem statement | 2 | T1 | |
| 6. | Linear Optimum Filtering | 1 | T1 | |
| 7. | Principle of Orthogonality - Minimum Mean Square Error | 1 | T1 | |
| 8. | Wiener- Hopf equations | 1 | T1 | |
| 9. | Error Performance - Minimum Mean Square Error | 1 | T1 | |
| | Total periods required: | 10 | | |
| | UNIT - II: SEARCHING THE PERFORMAN | ICE SURFA | CE & STEE | PEST DESCENT |
| | ALGORI | THMS | | |
| 10. | Methods & Ideas of Gradient Search methods, & its Solution | 2 | T1 | Three basic kinds of Estimation , linear |
| 11. | Gradient Searching Algorithm | 1 | T1 | optimum filters |
| 12. | Stability & Rate of convergence | 1 | T1 | |
| 13. | Learning Curves | 1 | T1 | |
| 14. | Gradient Search by Newton's Method | 1 | T1 | |
| 15. | Method of Steepest Descent | 1 | T1 | |
| 16. | Comparison of Learning Curves | 1 | T1 | |
| | Total periods required: | 8 | | |
| | UNIT -III: LMS& RL | S ALGORI | THMS | |
| 17. | Overview - LMS Adaptation algorithms | 1 | T1 | Characterization of the Autoregressive |
| 18. | Stability & Performance analysis of LMS | 2 | T1 | 2.00000 |
| 19. | LMS Gradient & Stochastic algorithms | 1 | T1 | |
| 20. | Noise cancellation, Cancellation of | | T2 | |



| | Echoes in long distance telephone | 2 | | |
|-----|--|---------|------------------|----------------------------|
| | circuits and Adaptive Beam forming | _ | | |
| 21. | Matrix Inversion lemma, exponentially | | T2 | |
| | weighted recursive least square | 2 | | |
| | algorithm | | | |
| 22. | update recursion for the sum of | 2 | T2 | |
| | weighted error squares | 2 | | _ |
| 23. | convergence analysis of RLS Algorithm | 2 | <u>T2</u> | _ |
| 24. | Application of RLS algorithm on | 1 | 12 | |
| | | 12 | | |
| | <u>UNIT – IV· KAI MAN FII TERING& NO</u> | | | |
| 25 | Introduction Recursive Mean Square | 2 | | Regularization |
| 20. | Estimation Pandom variables | 2 | 12 | Recursive |
| | | | | computation of time |
| 26. | The Innovations Process | 1 | T2 | average correlation |
| 27 | Estimation of the state using the | 2 | T2 | matrix, |
| 27. | Innovations Process | - | | |
| 28. | Filtering | 1 | T2 | - |
| | 1 | | | |
| 29. | Initial conditions | 1 | T2 | |
| | | | | _ |
| 30. | Variants of Kalman filtering | 2 | T2 | |
| 0.1 | Direct Descence better | | | _ |
| 31. | Blind Deconvolution | 1 | 12 | |
| 32 | Buss Gang Algorithm for blind | 2 | Т2 | _ |
| 52. | Equalization | 2 | 12 | |
| | Total periods required: | 12 | | |
| | UNIT – V: ORDER-RECURSI | VE ADAP | FIVE FILT | ERS |
| 33. | Gradient-Adaptive Lattice Filter | 2 | T2 | Sato Algorithm, |
| | 1 | | | Godard Algorithm |
| 34. | order-recursive adaptive filters using | 1 | T2 | |
| | least square estimation | | | Research Topics: |
| | least square estimation | | | |
| 35. | adaptive forward linear prediction | 2 | Т2 | Nonlinear System |
| 00. | adaptive backward linear prediction | - | | Identification, Signal and |
| 36 | conversion factor least-square lattice | 2 | Т2 | Information Processing |
| | predictor | 2 | 12 | C C |
| 27 | angle normalized astimation arrors | 1 | ТЭ | EEG |
| 20 | first order state grace models for lattice | 1 | | _ |
| 30. | first order state space models for fattice | I | 12 | Bio-acoustics and sonar |
| | | | | |
| 39. | QR-Decomposition-Based Least-Squares | 3 | 12 | Secure signal processing |
| | Lattice Filters, Recursive Least-Squares | | | |
| | lattice Filters Using a Posteriori | | | |
| | Estimation Errors | | | |
| | | | | |
| | Total periods required: | 12 | | 1 |
| | Grand total periods required: | 55 | | |

TEXT BOOKS:

- T1. Bernard Widrow, Samuel D. Strearns, Adaptive Signal Processing, PE, 1985.
- T2. Simon Haykin, *Adaptive Filter Theory*, 4th Edition, PE Asia, 2002.

REFERENCE BOOKS:

- R1. Alexander D Poularikas & zayed m Ramadan, CRC, *Adaptive Filtering Primer with MATLAB*, Taylor & Francis group.
- R2. Sophocles. J. Orfamadis, *Optimum signal processing: An introduction*, 2nd Edition, McGraw-Hill, Newyork, 1988.

Signature of the faculty Member framing the syllabus



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and Communication Engineering

Lesson Plan

Name of the Subject: Detection and Estimation of Signals (14MT23806) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: Ms. H.D.Praveena

| S. No. | Торіс | No. of | Book(s) | Topics for self study |
|--------|---|--------------|------------------|--------------------------|
| - | LINIT I Dat | periods | lollowed | |
| 1 | Maximum likelihood desision aritarian | | г у Т1 | Novmon Doorson |
| 1. | Maximum-fikelihood decision criterion | 1 | 11 | Neyman-Pearson |
| 2 | Norman Dearson aritarian | 2 | т1 | criterion for Radar |
| ۷. | Neyman-Pearson criterion | 2 | 11 | detection of variable |
| 2 | Duch chility of suman aritarian | 2 | T1 | amplitude signals, |
| 5. | Probability-of-error criterion | 2 | 11 | Conditional Probability |
| 1 | D 1 4 1 | 1 | T1 | density function, Bayes' |
| 4. | Bayes risk criterion | 1 | 11 | Theorem, Q Function. |
| | | 1 | T 1 | - |
| 5. | Min-max criterion | 1 | 11 | |
| | | | | - |
| 6. | Receiver operating characteristics | 2 | TI | |
| | | | | |
| 7. | Problems | 3 | T1 | |
| | | | | |
| | Total periods required: | 12 | | |
| | UNIT – II: Binary Decisio | ns: Multiple | Observation | S |
| 8. | Vector observations | 2 | T1 | Properties of Gaussian |
| | | | | Probability density |
| 9. | The general Gaussian problem | 2 | T1 | function, Concept of |
| | | | | Convolution, Whitening |
| 10. | Waveform Observation in Additive | 1 | T1 | Process. |
| | Gaussian Noise | 1 | | |
| | | | | |
| 11. | The Integrating Optimum Receiver | 2 | T1 | |
| | | | | |
| 12. | Matched Filter Receiver | 2 | T1 | |
| | | - | | |
| 13. | problems | 2 | T1 | |
| | problems | 2 | | |
| | Total periods required: | 11 | | |
| | UNIT -III: Esti | imation Theo | rv | |
| 14. | Maximum likelihood estimation | 1 | T1 | Mean & Median of |
| | With Michinobu estimation | 1 | | Conditional Probability |
| 15. | Bayes estimation criterion: Mean Square | | T1 | density function |
| 10. | Error Criterion | 1 | | Aultinle persector |
| | Error Criterion | | | Multiple parameter |
| 1.0 | | | | Estimation, Sequential |
| 16. | Uniform Cost Function | 1 | 11 | Estimation. |
| | | | | |
| 17. | Absolute-Value Cost Function | 1 | T1 | |
| | | | | |

| 18. | Linear Minimum-Variance Method | 2 | T1 | |
|-----|--|----------------|---------------|--|
| 19. | Least-Squares Method | 1 | T1 | |
| 20. | Estimation in the presence of Gaussian noise | 1 | T1 | |
| 21. | Linear observation | 1 | T1 | - |
| 22. | Non-linear estimation | 2 | T1 | |
| 23. | problems | 1 | T1 | |
| | Total periods required: | 12 | | |
| | UNIT – IV: Proper | rties Of Esti | mators | |
| 24. | Bias | 1 | T1 | Performance evaluation of Estimators when |
| 25. | Efficiency | 2 | T1 | imperfect source and |
| 26. | Cramer-Rao bound | 2 | T1 | channel models are used. |
| 27. | Asymptotic properties | 1 | T1 | |
| 28. | Sensitivity and error analysis | 1 | T1 | |
| 29. | Problems | 1 | T1 | - |
| | Total periods required: | 08 | | |
| | UNIT – V: State Estimation & St | tatistical Est | imation of Pa | rameters |
| 30. | State Estimation: Prediction | 2 | T1 | Binomial, Poisson, Uniform Gaussian |
| 31. | Kalman filter | 2 | T1 | Exponential, Rayleigh |
| 32. | Problems | 2 | T2 | Research topics: |
| 33. | Statistical Estimation of Parameters: Concept of sufficient statistics | 1 | R2 | Extended Kalman filter, Super resolution Array Processing. |
| 34. | Exponential families of Distributions | 1 | R2 | |
| 35. | Exponential families and Maximum likelihood estimation | 2 | R2 | |
| 36. | Uniformly minimum-variance unbiased estimation | 1 | R2 | |
| | Total periods required: | 11 | 1 | |
| | Grand total periods required: | 54 | | |

T1: James L.Melsa & David L.Cohn, "Decision and Estimation Theory", McGraw Hill, 1978.

T2: Steven M. Kay, "Fundamentals of Statistical Signal Processing Vol. 1: Estimation Theory, Prentice Hall, 1993, Vol. 2: Detection Theory," Prentice Hall Inc. 1998

1993, Vol. 2: Detection Theory", Prentice Hall Inc., 1998.

Reference Books:

- R1: Harry L. Van Trees, "Detection, Estimation and Modulation Theory", Part 1, John Wiley & Sons Inc. 1968.
- R2: Jerry M. Mendel, "Lessons in Estimation Theory for Signal Processing, Communication and Control", Prentice Hall Inc., 1995.
- R3: Sophocles J.Orfanidis, "Optimum Signal Processing", McGraw Hill, 2nd edition, 1988.

Signature of the faculty Member framing the syllabus



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

Lesson Plan

Name of the Subject: EMI/EMC (14MT26103) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: A.Nagaraju

| S.No | Topic | No. of | Book(s) | Topics for self study |
|----------|---|-------------|-------------|-----------------------|
| LINITT I | . Introduction and Sources of FMI and Nanid | perious | 10110Wed | anonta |
| | : Introduction and Sources of EMI and Nonio | | or of Comp | onents |
| 1. | Concepts and Definition of EWI and EWIC | 1 | 11 | Non ideal behaviour |
| 2 | Noticel and man made EMI sources | 2 | TT1 | of Forromagnetic |
| ۷. | Natural and man-made Elvir sources | 3 | 11 | Materiala Esprito |
| | | | | Roads |
| | | | | Electromachanical |
| 3. | Non-ideal behaviour of components-Wires, | 3 | 12 | Deviees |
| | printed circuit board (PCB) lands, effect of | | | Devices |
| | component leads | | | |
| 4. | Non ideal behaviour of resistors, capacitors, | 3 | T2 | |
| | inductors | | | |
| | | | | |
| | | | | |
| Total p | eriods required | 10 | | |
| UNIT-I | I: EMI/EMC Standards and Open Area Test | Sites | • | |
| 5. | Introduction - Standards for EMI/EMC, | 2 | T1 | |
| | MIL, STD 461 /462, IEEE/AXSI Standards, | | | |
| | CISPR/IEC Standards, FCC regulations | | | |
| 6. | open area test site measurements | 1 | T1 | |
| 7. | Measurement precautions ,open area test site | 2 | T1 | |
| | | | | |
| 8. | Terrain Roughness, Normalized Site | 2 | T1 | |
| | Attenuation, | | | |
| 9. | Measurement of test site imperfections | 2 | T1 | |
| | | | | |
| | | | | |
| 10. | Antenna factor measurement, Measurement | 1 | T1 | |
| | errors | | | |
| Total p | eriods required | 10 | | |
| UNIT-I | II: Radiated Interference and Conducted Inte | erference N | /leasuremen | nts |
| 11. | Anechoic chamber | 2 | T1 | Crosstalk |
| | | | | |
| 12. | Transverse Electromagnetic Cell | 2 | T1 | |
| | | | | |
| 13. | Reverberating chamber | 1 | T1 | |
| | | | | |
| 14. | Giga-Hertz TEM Cell | 1 | T1 | |
| 15 | Comparison of test facilities | 1 | Т1 | 4 |
| 13. | Comparison of conduction | 1 | T1 | 4 |
| 10. | currents/voltages | 1 | 11 | |
| 17 | Conducted EM noise on newer supply lines | 1 | Т1 | 4 |
| 17. | Conducted ENI noise on power supply lines | 1 | 11 | |

| 18. | Conducted EMI from equipment | 1 | T1 | |
|---------|---|---------|----|---|
| 19. | Immunity to conducted EMI, Detectors and measurement | 1 | T1 | _ |
| Total p | eriods required | 11 | | |
| UNIT – | IV: Grounding, Shielding and Bonding | | | |
| 20. | Principles and Practice of Earthing | 2 | T1 | |
| 21. | Precautions in Earthing, Measurements of ground resistance | 2 | T1 | |
| 22. | System grounding for EMC, Cable shield Grounding | 1 | T1 | |
| 23. | Shielding Theory and Effectiveness, , | 2 | T1 | |
| 24. | Shielding Materials, Shielding Integrity at discontinuities | 2 | T1 | |
| 25. | Conductive coatings, Cable shielding, Shielding Effectiveness measurements | 2 | T1 | |
| 26. | Electrical Bonding. | 2 | T1 | |
| Total p | eriods required | 13 | • | - |
| UNIT - | V: EMC Filters, Cables, Connectors and Con | nponent | s | |
| 27. | Characteristics and Types of Filters | 3 | T1 | Research Topic: New methods for calculating |
| 28. | Power Line filter Design - Common mode filter, Differential mode filter, Combined CM and DM filter | 1 | T1 | attenuation, Shielding effectiveness measurement |
| 29. | EMI suppression cables | 2 | T1 | techniques, EMI Noise filters |
| 30. | EMC connectors | 2 | T1 | |
| 31. | Knitted WireMesh Gaskets, Wire Screen Gaskets, Oriented Wire mesh, Conductive Elastomer, Transparent Conductive windows, Conductive Adhesive, Conductive Grease. Conductive Coatings. | 1 | T1 | |
| 32. | Isolation transformers. Opto Isolators. | 1 | T1 | |
| Total p | eriods required | 10 | | |
| Grand | total periods required: | 54 | | |

- T1: V.Prasad Kodali, "Engineering Electromagnetic Compatibility", S.Chand & company Ltd., 1st edition, 2000.
- T2: Clayton R. Paul, "Introduction to Electromagnetic Compatibility", John Wiley and Sons, 2nd edition, 2008.

Reference books

R1: Christos Christopoulos, "Principles and Techniques of Electromagnetic Compatibility", CRC Press (Taylor & Francis Group) 2nd edition, 2007.

Signature of the faculty Member framing the syllabus

Signature of the Chairman (BOS)



SREE VIDYANIKETHAN ENGINEERING COLLEGE (Autonomous) Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

Lesson Plan

Name of the Subject: Information Theory and Coding Techniques (14MT23802) Class & Semester: M. Tech. (CMS) – I Semester Name of the faculty Member: P.Padmaja

| S. | Торіс | No. of | Book(s) | Topics for self study |
|-----|---|----------|----------|------------------------|
| No. | | periods | followed | |
| | UNIT – I: INTRO | DUCTION | I | |
| 1. | Entropy: Discrete stationary sources, | 2 | T1 | |
| | Markov sources | | | |
| 2. | Entropy of a discrete Random variable- | 2 | T1 | |
| | Joint, conditional, relative entropy. | _ | | |
| | Mutual Information and conditional | | | |
| | mutual information | | | |
| 3. | Chain rules for entropy, relative entropy | 1 | T1 | The entropy power |
| | and mutual Information | | | inequality and the |
| 4. | Differential Entropy - Joint, relative, | 1 | T1 | Brunn–Minkowski |
| | conditional differential entropy and | | | Inequality, Lempel-Ziv |
| | Mutual information | | | coding, Arithmetic |
| 5. | Loss less Source coding: Uniquely | 1 | T1 | coding. |
| | decodable codes | | | |
| 6. | Instantaneous codes | 1 | T1 | |
| 7. | Kraft's inequality | 1 | T1 | |
| 8. | Optimal codes | 1 | T1 | |
| 9. | Huffman code | 1 | T1 | |
| 10. | Shannon's Source Coding Theorem | 1 | T1 | |
| | Total periods required: | 12 | | |
| | UNIT –II: CHANN | NEL CAPA | CITY | |
| 11. | Capacity computation for some simple channels | 1 | T1 | |
| 12 | Channel Coding Theorem | 1 | T1 | |
| 12. | Fano's inequality and the converse to the | 1 | T1 | |
| 10. | Coding Theorem, | | | |
| 14. | Equality in the converse to the coding | 1 | T1 | |
| | theorem | | | |
| 15. | The joint source Channel Coding | 1 | T1 | |
| | Theorem | | | Rate distortion |
| 16. | The Gaussian channels- Capacity | 2 | T1 | |

| | calculation for Band limited Gaussian | | | Theory, Arimoto- Blabut algorithm |
|---|--|---|--|---|
| 17. | Parallel Gaussian Channels | 2 | T1 | |
| 18. | Capacity of channels with colored | 1 | | |
| 10. | Gaussian noise | · | | |
| | Total periods required: | 10 | | |
| | UNIT -III: CHAN | NEL CODI | NG-1 | |
| 19. | Linear Block Codes: Introduction to Linear block codes | 1 | T2 | |
| 20. | Generator Matrix | 1 | T2 | |
| 21. | Systematic Linear Block codes | 1 | T2 | Fror probability after |
| 22. | Encoder Implementation of Linear Block Codes | 1 | T2 | decoding, Structured |
| 23. | Parity Check Matrix | 1 | T2 | the Standard Array. |
| 24. | Syndrome testing | 1 | T2 | |
| 25. | Error Detecting and correcting capability of Linear Block codes | 1 | T2 | _ |
| 26. | Application of Block codes for error control in data storage Systems | 1 | T2 | |
| | Total periods required: | 08 | | |
| | UNIT – IV: CHANNE | L CODIN(| G-2 | |
| 27. | Cyclic Codes: Algebraic Structure of Cyclic Codes | 1 | T2 | |
| | , | | | |
| 28. | Binary Cyclic Code Properties | 1 | T2 | Trellis-Coded |
| 28. 29. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register | 1 | T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), |
| 28. 29. 30. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register Error Detection with an (n - k)-Stage Shift Register | 1 1 1 | T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding, |
| 28. 29. 30. 31. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register Error Detection with an (n - k)-Stage Shift Register Well-Known Block Codes-Hamming Codes | 1 1 1 1 | T2 T2 T2 T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |
| 28. 29. 30. 31. 32. | Binary Cyclic Code PropertiesEncoding in Systematic Form ,SystematicEncoding with an (n - k)-Stage ShiftRegisterError Detection with an (n - k)-Stage ShiftRegisterWell-Known Block Codes-HammingCodesExtended Golay Code | 1 1 1 1 1 1 | T2 T2 T2 T2 T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |
| 28. 29. 30. 31. 32. 33. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register Error Detection with an (n - k)-Stage Shift Register Well-Known Block Codes-Hamming Codes Extended Golay Code BCH Codes | 1 1 1 1 1 1 1 | T2 T2 T2 T2 T2 T2 T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |
| 28. 29. 30. 31. 32. 33. 34. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register Error Detection with an (n - k)-Stage Shift Register Well-Known Block Codes-Hamming Codes Extended Golay Code BCH Codes Convolutional Codes: Convolution Encoding | 1 1 1 1 1 1 1 1 | T2 T2 T2 T2 T2 T2 T2 T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |
| 28. 29. 30. 31. 32. 33. 34. 35. | Binary Cyclic Code PropertiesEncoding in Systematic Form ,SystematicEncoding with an (n - k)-Stage ShiftRegisterError Detection with an (n - k)-Stage ShiftRegisterWell-Known Block Codes-HammingCodesExtended Golay CodeBCH CodesConvolutional Codes: ConvolutionEncodingConvolutional Encoder Representation | 1 1 1 1 1 1 1 1 1 | T2 T2 T2 T2 T2 T2 T2 T2 T2 T2 T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |
| 28. 29. 30. 31. 32. 33. 34. 35. 36. | Binary Cyclic Code Properties Encoding in Systematic Form ,Systematic Encoding with an (n - k)-Stage Shift Register Error Detection with an (n - k)-Stage Shift Register Well-Known Block Codes-Hamming Codes Extended Golay Code BCH Codes Convolutional Codes: Convolution Encoding Convolutional Encoder Representation Formulation of the Convolutional Decoding Problem | 1 1 1 1 1 1 1 1 1 1 1 | T2 T2 | Trellis-Coded Modulation-The Idea Behind Trellis-Coded Modulation (TCM), TCM Encoding, TCM Decoding. |

| 38. | Sequential Decoding | 1 | T2 | | | | | |
|-----|---|----------|------|----------------------------------|--|--|--|--|
| 39. | Feedback Decoding | 1 | T2 | | | | | |
| 40. | Application of Viterbi and sequential decoding. | 1 | T2 | | | | | |
| | Total periods required: 14 | | | | | | | |
| | UNIT – V: CHAN | NEL CODI | NG-3 | | | | | |
| 41. | Reed-Solomon Codes- Reed-Solom1on Error Probability | 1 | T2 | | | | | |
| 42. | Finite Fields, Reed-Solomon Encoding | 1 | T2 | | | | | |
| 43. | Reed-Solomon Decoding | 1 | T2 | | | | | |
| 44. | Interleaving and Concatenated Codes- | 1 | T2 | | | | | |
| | Block Interleaving | | | Research Topics: | | | | |
| 45. | Convolutional Interleaving | 1 | T2 | Applications of Reed | | | | |
| 46. | Concatenated Codes | 1 | T2 | Solomon codes in | | | | |
| 47. | Coding and Interleaving Applied to the Compact Disc Digital Audio System- CIRC Encoding | 1 | Τ2 | Deep space Telecommunications | | | | |
| 48. | CIRC Decoding | 1 | T2 | | | | | |
| 49. | Turbo Codes- Turbo Code Concepts | 1 | T2 | | | | | |
| 50. | Encoding with Recursive Systematic Codes | 1 | T2 | | | | | |
| 51. | A Feedback Decoder | 1 | T2 | | | | | |
| 52. | The MAP Decoding Algorithm | 1 | T2 | | | | | |
| | Total periods required: | 12 | | | | | | |
| | Grand Total periods required: | 56 | | | | | | |

T1: Thomas M. Cover and Joy A. Thomas, Elements of Information Theory, John Wiley & Sons, 1st Edition,1999.

T2: Bernard sklar, "Digital Communications – Fundamental and Application", Pearson Education, 2nd Edition, 2009.

Reference Books:

R1: John G. Proakis, "Digital Communications", Mc. Graw Hill Publication, 5th Edition, 2010. R2: SHU LIN and Daniel J. Costello, Jr., "Error Control Coding – Fundamentals and Applications", Prentice Hall, Second Edition, Prentice Hall, 2002.

R3: R. J. McEliece, The Theory of Information & Coding, Addison Wesley Publishing Co., 1977.

Signature of the faculty Member framing the syllabus



(Autonomous) Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

Lesson Plan

Name of the Subject: Radar Signal Processing (14MT26104) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: Ms.G. Madhavilatha

| S. | Торіс | No. of | Book(s) | Topics for self |
|-----|--|-------------|------------|----------------------------------|
| No. | | periods | followed | study |
| | | | | |
| | UNIT – I: RANGE EQUATIO | N AND MATCI | HED FILTER | |
| | | | | |
| 1. | Introduction to Radar | 1 | Т3 | System losses, Probability of |
| 2. | Radar Block Diagram | 1 | Т3 | detection and false |
| 3. | Radar Equation, Information Available from Radar Echo | 1 | Т3 | of radar |
| 4. | Review of Radar Range Performance– General Radar Range Equation | 1 | T2 | |
| 5. | Radar Detection with Noise Jamming | 1 | T2 | |
| 6. | Beacon and Repeater Equations | 1 | T2 | |
| 7. | Bistatic Radar | 1 | T2 | |
| 8. | Matched Filter Receiver – Impulse Response | 1 | T1 | |
| 9. | Frequency Response Characteristic and its Derivation | 1 | T1 | |
| 10. | Matched Filter and Correlation Function | 1 | T1 | |
| 11. | Correlation Detection and Cross-Correlation Receiver | 1 | T1 | |
| 12. | Efficiency of Non-Matched Filters | 1 | T1 | |

| 13. | Matched Filter for Non-White Noise | 1 | T1 | |
|-----|---|-------------|------------|--|
| | Total periods required: | 13 | | |
| | | | | |
| | UNIT - II: DETECTION OF RA | DAR SIGN | IALS IN NO | DI SE |
| 14. | Detection Criteria – Neyman-Pearson Observer | 1 | T1 | Integrators- Moving window, binary integration. |
| 15. | Likelihood-Ratio Receiver, Inverse Probability Receiver | 1 | T1 | |
| 16. | Sequential Observer | 1 | T1 | |
| 17. | Detectors –Envelope Detector, Logarithmic Detector, I/Q Detector | 2 | T1 | |
| 18. | Automatic Detection - CFAR Receiver | 1 | T1 | |
| 19. | Cell Averaging CFAR Receiver | 1 | T1 | |
| 20. | CFAR Loss, CFAR Uses in Radar | 1 | T1 | |
| 21. | Schematics, Component Parts, Resources and Constraints | 2 | T1 | |
| | Total periods required: | 10 | 1 | |
| | UNIT III: WAVEFO | RM SELECTIO | N | |
| 22. | Radar Ambiguity Function and Ambiguity Diagram – Principles and Properties | 2 | T1 | Weather clutter, sea clutter, other sources of atmospheric echoes |
| 23. | Specific Cases – Ideal Case, Single Pulse of Sine Wave | 1 | T1 | |
| 24. | Periodic Pulse Train, Single Linear FM Pulse, Noise like Waveforms | 1 | T1 | |
| 25. | Waveform Design Requirements | 1 | T1 | |

| 26. | Introduction to clutter, surface clutter | 2 | T1 | |
|-----|---|--------------|-----------|---------------------------------------|
| 27. | Land clutter | 1 | T1 | |
| 28. | Detection of targets in clutter | 1 | T1 | - |
| | Total periods required: | 09 | | |
| | UNIT IV: PULSE COMPRESS | SION IN RADA | R SIGNALS | |
| 29. | Introduction, Significance, Types | 1 | T1 | Factors affecting the |
| 30. | Linear FM Pulse Compression – Block Diagram | 1 | T1 | choice of pulse compression system |
| 31. | Linear FM Pulse Compression – Characteristics | 1 | T1 | |
| 32. | Reduction of Time Side lobes, Stretch Techniques | 2 | T1 | |
| 33. | Generation and Decoding of FM Waveforms – Block Schematic and Characteristics of Passive System | 1 | T2 | |
| 34. | Digital Compression | 1 | Т3 | |
| 35. | SAW Pulse Compression | 1 | T3 | |
| | Total periods required: | 08 | 1 | |
| | UNIT V: PHASE COD | ING TECHNIC | QUES | |
| 36. | Principles, Binary Phase Coding | 1 | T2 | Welti codes, variants of barker code |
| 37. | Barker Codes | 1 | T2 | comparison of pulse |
| 38. | Maximal Length Sequences (MLS/LRS/PN) | 1 | T2 | waveforms. |
| 39. | Block Diagram of a Phase Coded CW Radar | 1 | T2 | Research Topics: |
| 40. | Poly phase codes- Frank Codes, Costas Codes | 1 | T1 | Radars & Imaging |
| 41. | Non-Linear FM Pulse Compression | 1 | T1 | hadar s |
| 42. | Doppler Tolerant PC Waveforms – Short Pulse | 1 | T1 | |

| 43. | Linear Period Modulation (LPM/HFM) | 1 | T1 | |
|-----|---|----|----|---|
| 44. | Sidelobe Reduction for Phase Coded PC Signals | 1 | T1 | |
| 45. | Complementary Codes, Huffman Codes | 1 | T1 | |
| 46. | Limiting in Pulse Compression | 1 | T1 | |
| 47. | Cross-Correlation Properties, Compatibility | 1 | T1 | |
| | Total periods required: | 13 | 1 | I |
| | Grand total periods required: | 53 | | |

TEXT BOOKS:

- T1. M.I. Skolnik, "Introduction to Radar Systems", TMH, 3rd Edition, 2001.
- T2. Fred E. Nathanson, "*Radar Design Principles Signal Processing and The Environment*", McGraw Hill, Inc, 2nd Edition, 1991.
- T3. M.I. Skolnik, Radar Handbook, McGraw Hill, 2nd Edition, 1991.

REFERENCE BOOKS:

R1. Peyton Z. Peebles Jr, "Radar Principles", John Wiley, 1998.

R2. R. Nit berg, Radar Signal Processing and Adaptive Systems, Artech House, 1999.

R3. F.E. Nathanson, Radar Design Principles, 1st Edition, McGraw Hill, 1969

Signature of the faculty Member Framing the syllabus



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

<u>Lesson Plan</u>

Name of the Subject: Software Defined Radio (14MT26102) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: Dr. V. R. Anitha

| S. No. | Торіс | No. of periods | Book(s) followed | Topics for self study | | | |
|-----------|--|-------------------|---------------------|---|--|--|--|
| | UNIT – I: INTRODUCTION TO SOFTWARE RADIO CONCEPTS | | | | | | |
| 1. | The need for Software radios and its definition | 1 | T1 | | | | |
| 2. | Characteristics and benefits of Software radio | 1 | T1 | | | | |
| 3. | Design principles of a software radio. | 1 | T1 | | | | |
| 4. | Radio Frequency Implementation Issues : Purpose of RF front – end | 1 | T1 | | | | |
| 5. | Dynamic range | 1 | T1 | Issues in spectrum | | | |
| 6. | RF receiver front – end topologies | 2 | T1 | sensing, Sensing | | | |
| 7. | Enhanced flexibility of the RF chain with software radios, Importance of the components to overall performance | 2 | T1 | interference limit | | | |
| 8. | Transmitter architectures and their issues | 1 | T1 | | | | |
| 9. | Noise and distortion in the RF chain | 2 | T1 | | | | |
| 10. | ADC & DAC distortion, Pre-distortion | 1 | T1 | | | | |
| 11. | Flexible RF systems using micro- electromechanical systems | 1 | T1 | | | | |
| | Total periods required: | 14 | | | | | |
| | UNIT – II: MULTIRATE SIG | NAL PROC | ESSING IN S | SDR | | | |
| 12. | Sample rate conversion principles | 2 | T1 | Digital filtering, | | | |
| 13. | Polyphase filters | 2 | T1 | spectral analysis, | | | |
| 14. | Digital filter banks | 2 | T1 | appled to digital | | | |
| 15. | Timing recovery in digital receivers using multirate digital filters | 2 | T1 | conversion | | | |
| | Total periods required: | 08 | | | | | |
| | UNIT -III: DIGITAL GEN | ERATION (| OF SIGNALS | 5 | | | |
| 16. | Introduction | 1 | T1 | | | | |
| 17. | Comparison of direct digital synthesis with analog signal synthesis | 1 | T1 | Cine altere and | | | |
| 18. | Approaches to direct digital synthesis | 2 | T1 | Modified Sine-phase Difference Algorithm | | | |
| 19. | Analysis of spurious signals | 2 | T1 | Approach | | | |
| 20. | Spurious components due to periodic jitter | 1 | T1 | | | | |
| 21. | Bandpass signal generation | 1 | T1 | | | | |
| 22. | Performance of direct digital synthesis systems | 1 | T1 | | | | |

| 23. | Hybrid DDS – PLL Systems | 1 | T1 | |
|---|--|--|---|---|
| 24. | Applications of direct digital synthesis | 1 | T1 |] |
| 25. | Generation of random sequences | 1 | T1 | |
| 26. | ROM compression techniques | 1 | T1 | |
| | Total periods required: | 13 | | |
| | UNIT – IV: SMA | RT ANTENI | NAS | |
| 27. | Introduction | 1 | T1 | |
| 28. | Vector channel modelling | 1 | T1 | |
| 29. | Benefits of smart antennas, Structures for beamforming systems | 1 | T1 | |
| 30. | Smart antenna algorithms | 1 | T1 | |
| 31. | Diversity and Space time adaptive signal processing | 1 | T1 | Trade-offs in using DSPs, FPGAs, and |
| 32. | Algorithms for transmit STAP | 2 | T1 | ASICs |
| 33. | Hardware implementation of smart antennas | 1 | T1 | _ |
| 34. | Array calibration | 1 | T1 | _ |
| 35. | Digital Hardware Choices - Key hardware elements | 1 | T1 | |
| 36. | DSP processors, FPGAs | 2 | T1 | |
| 37. | Power management issues | 1 | | |
| | Total periods required: | 13 | | |
| - | | | | |
| 1 | UNIT – V: OBJECT ORIENTED REPRESE | NTATION | OF RADIOS | AND NETWORK |
| 38. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming | NTATION 1 | OF RADIOS T1 | AND NETWORK |
| 38. 39. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers | NTATION (1 1 | OF RADIOS T1 T1 | AND NETWORK |
| 38. 39. 40. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments | NTATION 1 1 1 | OF RADIOS T1 T1 T1 T1 | AND NETWORK |
| 38. 39. 40. 41. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. | NTATION (1 1 1 1 | OF RADIOS T1 T1 T1 T1 T1 T1 | AND NETWORK |
| 38. 39. 40. 41. 42. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy | NTATION (1 1 1 1 1 1 | OF RADIOS T1 T1 T1 T1 T1 T1 T1 | CHARIOT Research Topics : |
| 38. 39. 40. 41. 42. 43. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. | NTATION (1 1 1 1 1 1 1 1 | OF RADIOS T1 | AND NETWORK CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum |
| 38. 39. 40. 41. 42. 43. 44. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. Wireless Information transfer system | NTATION (1 1 1 1 1 1 1 1 1 1 | T1 | CHARIOT CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum management issues |
| 38. 39. 40. 41. 42. 43. 43. 44. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. Wireless Information transfer system SDR-3000 digital transceiver subsystem | NTATION (1 1 1 1 1 1 1 1 1 1 1 1 | DF RADIOS T1 T1 T1 T1 T1 T1 T1 T1 T1 T1 | CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum management issues |
| 38. 39. 40. 41. 42. 43. 43. 44. 45. 46. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. Wireless Information transfer system SDR-3000 digital transceiver subsystem Spectrum Ware | NTATION (1 1 1 1 1 1 1 1 1 1 1 1 1 | DF RADIOS T1 T1 T1 T1 T1 T1 T1 T1 T1 T1 | CHARIOT CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum management issues |
| 38. 39. 40. 41. 42. 43. 43. 44. 45. 46. 47. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. Wireless Information transfer system SDR-3000 digital transceiver subsystem Spectrum Ware Brief introduction to Cognitive Networking | NTATION (1 1 1 1 1 1 1 1 1 1 1 1 1 | OF RADIOS T1 T1 | CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum management issues |
| 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. | UNIT – V: OBJECT ORIENTED REPRESE Networks, Object –oriented programming Object brokers Mobile application environments Joint Tactical radio system. Case Studies in Software Radio Design: SPEAKeasy JTRS , Brief introduction to Cognitive Networking. Wireless Information transfer system SDR-3000 digital transceiver subsystem Spectrum Ware Brief introduction to Cognitive Networking Total periods required: | NTATION (1 1 1 1 1 1 1 1 1 1 1 1 1 | OF RADIOS T1 | CHARIOT Research Topics : Spectrum Sensing in Multichannel Networks, Spectrum management issues |

- T1: Jeffrey Hugh Reed, "Software Radio: A Modern Approach to Radio Engineering," Prentice Hall Professional, 2002.
- T2: Paul Burns, "Software Defined Radio for 3G," Artech House, 2002.

Reference Books:

R1: Tony J Rouphael, "RF and DSP for SDR," Elsevier Newnes Press, 2008.R2: P. Kenington, "RF and Baseband Techniques for Software Defined Radio," Artech House, 2005.

Signature of the faculty Member framing the syllabus

Signature of the Chairman (BOS)



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and Communication Engineering

Lesson Plan

Name of the Subject: TELEMETRY AND TELECONTROL (14MT26105)

Name of the faculty Member: G. Guru Prasad

Class & Semester: M.Tech & II Semester

Specialization: CMS

| S. No. | Торіс | No. of | Book(s) | Topics for self study |
|--------|--|---------------|-----------|-----------------------|
| | T (D) () () | periods | followed | |
| UNIT – | I: Telemetry Principles | 1 | | 1 |
| 1. | Introduction | 1 | | comparators |
| 2. | Functional blocks of Telemetry system | 2 | TI | - |
| 3. | Classification of Telemetry systems | 1 | TI | - |
| 4. | Non Electrical Telemetry systems | 1 | <u>T1</u> | - |
| 5. | Electrical, Pneumatic Telemetry systems | l | TI | - |
| 6. | Frequency Telemetry systems | 1 | <u>T1</u> | 4 |
| 7. | Power Line Carrier Communication | 1 | T1 | |
| | Total periods required: | 08 | | |
| UNIT – | II: Symbols And Codes | - | | 1 |
| 8. | Bits and Symbols | 1 | T1 | Manchester encoding |
| 9. | Time function pulses | 1 | T1 | _ |
| 10. | Line and Channel Coding | 2 | T1 | _ |
| 11. | Modulation Codes | 2 | T1 | |
| | | | | - |
| 12. | Intersymbol Interference | 1 | T1 | |
| | Total periods required: | 07 | | |
| UNITI | II: Frequency Division & Time Division Multi | iplxed Syster | ns | |
| 13. | FDM system | 1 | TI | Phase locked loop |
| 14. | IRIG Standard | 1 | T1 | - |
| 15. | FM Circuits using varactor diode | 1 | T1 | |
| 16. | FM Circuits using clap oscillator | 1 | T1 | - |
| 17. | Reactance variation type PM circuit | 1 | T1 | - |
| 18. | Transistor type PM circuit | 1 | T1 | - |
| 19. | PLL demodulator | 1 | T1 | - |
| 20. | TDM-PAM systems | 1 | T1 | - |
| 21. | PAM and PM systems | 1 | T1 | - |
| 22. | PCM reception | 1 | T1 | - |
| 23. | Differential PCM | 1 | T1 | |
| | | | | |
| 24. | QAM Protocols | 2 | T1 | |
| | Total periods required: | 13 | | |
| UNIT I | V: Satellite & Optical Telemetry | | | |
| 25. | General considerations | 1 | T1 | FDMA, TDMA, CDMA |
| 26. | TT&C Service | 1 | T1 | |

| 27. | Digital Transmission systems | 2 | T1 | |
|--------|---|----|----|------------------------|
| 28. | TT&C Subsystems | 2 | T1 | - |
| | | | | |
| 29. | satellite Telemetry and Communications | 1 | T1 | |
| 30. | Optical fibers Cable – dispersion, losses | 1 | T1 | |
| 31. | connectors and splicers | 1 | T1 | |
| 32. | Sources and detectors | 1 | T1 | |
| | Total periods required: | 10 | | |
| UNIT V | 7: Telecontrol Methods | | | |
| 33. | Analog techniques in Telecontrol | 2 | T2 | Research topics: Radio |
| 34. | Digital techniques in Telecontrol | 2 | T2 | telemetry and remote |
| 35. | Remote adjustment | 2 | T2 | control, long range |
| 36. | Guidance and regulation | 2 | T2 | closed loop telemetry. |
| 37. | Telecontrol using information theory | 2 | T2 | |
| 38. | Example of a Telecontrol System | 2 | T2 | |
| | | | | |
| | | 12 | | |
| | Total periods required: | 50 | | |
| | Grand total periods required: | | | |

TEXT BOOKS:

- T1. D. Patranabis, Telemetry Principles, Tata McGraw-Hill, 1999
- T2. Swoboda G., Telecontrol Methods and Applications of Telemetry and Remote Control, Reinhold Publishing Corp., London, 1991

REFERENCES:

- R1. Gruenberg L., Handbook of Telemetry and Remote Control, McGraw Hill, New York, 1987.
- R2. Young R.E., Telemetry Engineering, Little Books Ltd., London, 1988.
- R3. Housley T.,Data Communication and Teleprocessing System, PH Intl., Englewood Cliffs, New Jersey, 1987.

Signature of the faculty Member framing the syllabus



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and Communication Engineering

Lesson Plan

Name of the Subject: Wireless Communications (14MT23805) Class & Semester: M. Tech. (DECS & CMS) – II Semester Name of the faculty Member: Dr. C. Subhas

| S. | Торіс | No. of | Book(s) | Topics for self study | | | |
|-----|--|----------|----------|------------------------|--|--|--|
| No. | | periods | followed | | | | |
| UI | UNIT – 1: INTRODUCTION TO WIRELESS COMMUNICATION SYSTEMS AND | | | | | | |
| | CELLULAR | CONCEPT | · | | | | |
| 1. | Evolution of Mobile Radio | 1 | T1 | Mobile radio systems | | | |
| | Communication Systems | | | around the world, | | | |
| 2. | Examples of Wireless Communication | 1 | T1 | WIAN Bluetooth and | | | |
| | Systems | | | PANs Handoff | | | |
| 3. | Wireless Cellular Networks and | 1 | T1 | strategies. | | | |
| | Standards – 1G | | | | | | |
| 4. | 2G | 1 | T1 | | | | |
| 5. | 2.5G | 1 | T1 | | | | |
| 6. | 3G | 1 | T1 | | | | |
| 7. | Frequency Reuse Concept | 1 | T1 | | | | |
| 8. | Channel Assignment Strategies | | T1 | | | | |
| 9. | Interference and System Capacity | 2 | T1 | | | | |
| 10. | Trunking and Grade of Service | 1 | T1 | | | | |
| 11. | Improving Coverage and Capacity in | 1 | T1 | | | | |
| | Cellular Systems - cell splitting and | | | | | | |
| | sectoring | | | | | | |
| | Total periods required: | 11 | | | | | |
| | UNIT – II: MOBILE RA | DIO PROP | AGATION | | | | |
| 12. | Large Scale Path Loss: Introduction | 1 | T1 | Simulation of Clarke's | | | |
| 13. | Free Space Propagation Model | | T1 | and Jake's models. | | | |
| 14. | Relating Power to Electric field | 1 | T1 | | | | |
| 15. | Propagation Mechanisms – Reflection | 2 | T1 | | | | |
| 16. | Diffraction and Scattering | 1 | T1 | | | | |
| 17. | Practical Budget Design using Path Loss | 1 | T1 | | | | |
| | Models | | | | | | |
| 18. | Outdoor Propagation Models | 1 | T1 | | | | |
| 19. | Indoor Propagation Models | 1 | T1 | | | | |
| 20. | Small Scale Fading and Multinath | 1 | T1 | | | | |
| | Small Scale Multipath Propagation | - | | | | | |
| 21. | Impulse Response Model of a Multipath | 1 | T1 | | | | |
| | Channel | | | | | | |
| 22 | Small Scale Multinath Measurements | 1 | T1 | | | | |
| 22. | Parameters of Mobile Channels | 1 | T1 | | | | |
| 23. | Turnes of Small Scale Feding (all | 1 | T1 | | | | |
| 24. | rypes of Sinan Scale Fauling (all | | | | | | |
| 25 | Valiational Modela Clarks's Model for | 1 | T1 | | | | |
| 25. | Siansticat Models – Clarke's Model for | | | | | | |
| | | 1 | + | | | | |
| 26. | | | Â | | | | |
| | Total periods required: | 15 | | | | | |

| | UNIT -III: EQUALIZATION & | DIVERSI | FY TECHN | IQUES |
|-----|--|----------------|-----------------|-------------------------|
| 27. | Equalization: Introduction, Survey of | | T1 | Fundamentals of |
| | Equalization Techniques | | | Equalization, Training |
| 28. | Linear Equalizers – Linear Transversal | | T1 | a generic adaptive |
| | Equalizer | 2 | | equalizer, Fractionally |
| 29. | Non-linear Equalizers - Decision | | T1 | Spaced Equalizers. |
| | Feedback Equalizer (DFE) | | | |
| 30. | Algorithms for Adaptive Equalization – | | T1 | |
| | Zero Forcing | | | |
| 31. | LMS | 2 | T1 | |
| 32. | RLS | | T1 | |
| 33. | Diversity Techniques : Realization of | 1 | T2 | |
| | Independent Fading Paths | | | |
| 34. | Receiver Diversity – System Model | 1 | T2 | |
| 35. | Selection Combining and Threshold | 1 | T2 | |
| | Combining | | | |
| 36. | Maximal Ratio Combining and Equal | 1 | T2 | |
| | Gain Combining | | | |
| 37. | Rake receiver | 1 | T1 | |
| 38. | Transmit Diversity-Channel known at | 1 | T2 | |
| | Transmitter | | | |
| 39. | Channel unknown at Transmitter – the | 1 | T2 | |
| | Alamouti Scheme, analysis. | | | |
| | Total periods required: | 11 | | |
| | UNIT – IV: MULTIPLE ACCESS T | ECHNIQU | ES & NET | WORKING |
| 40. | Introduction to Multiple Access: | 1 | T1 | FDD and TDD duplex |
| | FDMA, TDMA, | | | techniques, Capture |
| 41. | CDMA and SDMA | 1 | T1 | effect in packet radio, |
| 42. | Packet Radio-Pure ALOHA, Slotted | 1 | T1 | 15DN, 557. |
| | ALOHA | | | |
| 43. | CSMA, and reservation protocols. | 1 | T1 | |
| 44. | Capacity of Cellular Systems – Cellular | 1 | T1 | |
| | CDMA | | | |
| 45. | Introduction to Wireless Networking: | 1 | T2 | |
| | Introduction to Wireless Networks | | | |
| 46. | Differences between Wireless and Fixed | 1 | T2 | |
| | Telephone Networks | | | |
| 47. | Development of Wireless Networks | 1 | T2 | |
| 48. | Traffic Routing in Wireless Networks | 2 | T2 | |
| 49. | Wireless Data Services | 1 | T2 | |
| 50. | Common Channel Signaling | 1 | T2 | |
| | Total periods required: | 12 | | |
| | UNIT – V: MULTICAR | RIER MOD | ULATION | |
| 51. | Data Transmission using Multiple | 1 | T2 | Mitigation of |
| | Carriers | | | subcarrier fading, |
| 52. | Multicarrier Modulation with | 1 | T2 | IEEE 802.118 WLAN |
| | Overlapping Subchannels | | | study. |
| 53. | Discrete Implementation of Multicarrier | 1 | T2 | Research Topics: |
| | Modulation – DFT and its properties | | | MIMO wireless |
| 54. | The Cyclic Prefix | 1 | T2 | Systems, Cognitive |
| 55. | Orthogonal Frequency Division | 1 | T2 | Radio. |
| | Multiplexing (OFDM) | | | |
| 56. | Matrix Representation of OFDM | 1 | T2 | |

| 57. Vector Coding | 1 | T2 | |
|--|----|----|--|
| 58. Challenges in Multicarrier Systems | 1 | T2 | |
| Total periods required: | 08 | | |
| Grand total periods required: | 57 | | |

*Handout will be given.

Text Books:

T1: T. S. Rappaport, "Wireless Communications, Principles and Practice," Prentice Hall, 2nd Edition, 2002.

T2: Andrea Goldsmith, "Wireless Communications," Cambridge University Press, 2005.

Reference Books:

R1: David Tse, PramodViswanath, "Fundamentals of Wireless Communications," University Press, 2006.

R2: Dr. Kamilo Feher, "Wireless Digital Communications," Prentice Hall, 1995.

Signature of the faculty Member framing the syllabus



(Autonomous)

Sree Sainath Nagar, A. Rangampet-517 102

Department of Electronics and communication Engineering

Lesson Plan

Name of the Subject: Wireless Sensor Networks (14MT257709) Class & Semester: M. Tech. (CMS) – II Semester Name of the faculty Member: Dr. V. R. Anitha

| S. No | Торіс | No. of | Book(s) followed | Topics for self study |
|------------------|--|-----------|---------------------|-----------------------|
| 140. | UNIT – I: INTRODUCTION TO W | RELESS SI | ENSOR NET | WORKS |
| 1 | Challenges for wireless sensor networks | 1 | T1 | |
| 2. | Comparison of sensor network with ad hoc network | 1 | T1 | |
| 3. 4. | Single node architecture - Hardware components | 2 | T1 | |
| 5. 6. | Energy consumption of sensor nodes | 2 | T1 | Security in Sensor |
| 7. | Network architecture: Sensor network scenarios - types of sources and sinks | 1 | T1 | networks |
| 8. | Single hop versus multi-hop networks, multiple sinks and sources | 1 | T1 | |
| 9. 10. 11. | Design principles for wireless sensor networks | 3 | T1 | |
| | Total periods required: | 11 | | |
| | UNIT – II: PHYSI | | 2 | |
| 12. | Introduction, wireless channel and communication fundamentals | 1 | T1 | |
| 13. | Frequency allocation | 1 | T1 | |
| 14. | Modulation and demodulation | 1 | T1 | |
| 15. | Wave propagation effects and noise, | 1 | T1 | |
| 16. | Channels models | 1 | T1 | |
| 17. | Spread spectrum communication | 1 | T1 | Localization, IEEE |
| 18. | Packet transmission and synchronization | 1 | T1 | 802.15.4 low rate |
| 19. | Quality of wireless channels and measures for improvement | 1 | T1 | WPAN |
| 20. | Physical layer and transceiver design consideration in wireless sensor networks - Energy usage profile | 1 | T1 | |
| 21. | Choice of modulation, Power | | | |
| 22. | Management. | 2 | T1 | |
| | Total periods required: | 11 | 1 | |
| | UNIT -III: DATA LINK LAYE | R | | |
| 23. | MAC protocols: fundamentals of wireless MAC protocols | 2 | T1 | Practical |
| 24. | Requirements and design constraints for wireless MAC protocols | | | implementation issues |

| 25. | Important classes of MAC protocols, | 1 | T1 | |
|-----|--|----------|-----|---|
| 26. | MAC protocols for wireless sensor networks | 1 | T1 | |
| 27. | Low duty cycle protocols and wakeup concepts | 1 | T1 | |
| 28. | Sparse topology and energy management (STEM) | 1 | T1 | |
| 29. | S-MAČ | 1 | T1 | |
| 30. | Wakeup radio concepts | 1 | T1 | |
| 31. | Contention-based protocols - CSMA protocols | 1 | T1 | |
| 32. | PAMAS | 1 | T1 | |
| 33. | Schedule-based protocols - SMAC, BMAC | 1 | T1 | |
| 34. | Traffic-adaptive medium access protocol (TRAMA) | 1 | T1 | |
| 35. | Link Layer protocols – fundamentals task and requirements | 1 | T1 | |
| 36. | Error control - Causes and characteristics of transmission errors, ARQ techniques, | 1 | T1 | |
| 37. | FEC techniques | 1 | T1 | |
| 38. | Hybrid schemes, Power control | 1 | T1 | |
| | Total periods required: | 16 | | |
| | UNIT – IV: NET | WORK LAY | ER | |
| | Gossiping and agent-based uni-cast | | | |
| 39. | forwarding - Basic idea, Randomized forwarding, Energy-efficient unicast | 1 | T1 | |
| 40. | Broadcast and multicast - Source-based tree protocols | 1 | T1 | |
| 41. | Shared, core-based tree protocols, Mesh-based protocols | 1 | T1 | |
| 42. | Geographic routing - Basics of position- based routing | 1 | T1 | |
| 43. | Geocasting | 1 | T1 | |
| 44. | Mobile nodes - Mobile sinks, Mobile data collectors | 1 | T1 | |
| 45. | Mobile regions | 1 | T1 | |
| 46. | Data centric and content-based networking - Introduction | 1 | T1 | |
| 47. | Data-centric routing | 1 | T1 | |
| 48. | Data aggregation | 1 | T1 | |
| | Total periods required: | 10 | | |
| | UNIT – V: TRAN | SPORT LA | YER | |
| 49. | The transport layer and QoS in wireless sensor networks - Quality of service/reliabilitym, Transport protocols | 1 | T1 | Sensor Node Hardware- Node-level software platforms |
| 50. | Coverage and deployment - Sensing models, Coverage measures | 1 | T1 | standardization: IEEE 802.15.4 & IEEE |
| 51. | Uniform random deployments: Poisson point processes, Coverage of random deployments: Boolean sensing model, general sensing model | 2 | T1 | 802.11 Research Topics: Node-level simulators Wireless Sensor |

| 50 | Coverage determination, Coverage of | | T1 | Networks |
|-----|---|----|----|----------|
| 52. | grid deployments, Reliable data transport | 1 | T1 | |
| 53. | Single packet delivery - Using a single | 1 | T1 | |
| - | path, Multiple paths, Multiple receivers | | | |
| | Congestion control and rate control - | 1 | | |
| 54. | Congestion situations in sensor networks | I | | |
| | Mechanisms for congestion detection | 1 | T1 | |
| 55. | and handling | I | | |
| 56. | Protocols with rate control | 1 | | |
| 57. | The CODA congestion-control framework | 1 | | |
| | Total periods required: | 09 | | |
| | Grand total periods required: | | Ę | 57 |

T1: Holger Karl , Andreas willig "Protocol and Architecture for Wireless Sensor Networks", John wiley publication, Oct 2007.

Reference Books:

- R1: Feng zhao, Leonidas guibas, Elsivier, "Wireless Sensor Networks: an information processing approach –publication, 2004.
- R2: Edgar H .Callaway, First Edition,"Wireless Sensor Networks : Architecture and protocol", CRC press 2003.
- R3: C.S.Raghavendra Krishna, M.Sivalingam and Tarib znati, "Wireless Sensor Networks", Springer publication, 2006

Signature of the faculty Member framing the syllabus